

Symmetric spaces

I. Symmetric space A **symmetric space** is a pseudo Riemannian manifold M , so that for every $m \in M$, there exists a (unique) isometry I_m (the **symmetry** at m) so that $I_m(m) = m$; $T_m I_m = -\text{Id}$. It is of **non compact type** if it is Riemannian and the curvature $K \leq 0$; It is **without Euclidian factors** if one cannot write isometrically $M = N \times \mathbb{R}$ (metric product)

Examples: in $\dim 2$, \mathbb{R}^2 , S^2 , \mathbb{H}^2 , $[\mathbb{R}^{1,1}, \text{SL}_2(\mathbb{R})/\Delta = \{\text{space of geodesics}\}]$,
"symmetric space" will mean Riemannian space of non compact type (without euclidian factors), thus only \mathbb{H}^2 in the list.

Theorem let M be a symmetric space then

(i) M is complete and $G = \text{Iso}(M)$ acts transitively on M

(ii) every element $m \in M$ defines a splitting

$$\mathfrak{g} = \mathfrak{k}_m \oplus \mathfrak{p}_m \text{ where } \text{ad}(I_m)|_{\mathfrak{k}} = \text{Id} \quad \text{ad}(I_m)|_{\mathfrak{p}} = -\text{Id}$$

(iii) Using $\mathfrak{g} \hookrightarrow \mathcal{X}(M)$ (vector fields on M)

$$\mathfrak{k}_m = \{ \xi \mid \xi(m) = 0 \}$$

◀ undergraduate exercise ▶

Goal: (1) Construct the symmetric space associated to semi-simple groups (ex: $\text{SL}_n(\mathbb{R})$)
(e) Describe them from a Gauge theoretic point of view.

II. Preliminaries on semi-simple groups [admitted from Humphreys]

let G be a lie group and \mathfrak{g} its lie algebra

$G \curvearrowright \mathfrak{g}$ the adjoint action $g, a \mapsto \text{Ad}(g) \cdot a$

For $G \subset \text{GL}_n(\mathbb{K})$; $\mathfrak{g} \subset \mathfrak{M}_n(\mathbb{K})$; $\text{Ad}(g)a = gag^{-1}$

$\mathfrak{g} \curvearrowright \mathfrak{g}$ the adjoint action

$a, b \mapsto [a, b] = \text{Ad}(a) \cdot b$

For a linear group $[X, Y] = XY - YX$.

The Killing metric on \mathfrak{g} : $\kappa(X, Y) = \text{Tr}(\text{Ad}(X) \cdot \text{Ad}(Y))$

A group or lie algebra is **semi-simple** if κ is non degenerate

A lie algebra is **simple** if it does not contain an ideal

A group G is **almost simple** if \mathfrak{g} is simple

(Δ confusion about $\mathbb{R} \dots$)

\mathfrak{g} semi-simple $\Leftrightarrow \mathfrak{g} = \bigoplus_i \mathfrak{g}_i$ where \mathfrak{g}_i are simple ($\neq \mathbb{R}$)

A group is **adjoint** if Ad is injective

ex: $\text{SL}_n(\mathbb{R})$ is not adjoint, $\text{PSL}_n(\mathbb{R})$ is

A group is **linear**, if it admits an injective $\rho \hookrightarrow \text{GL}_n(\mathbb{R})$

All groups are now assumed to be linear

\rightarrow every G -invariant quadratic form on \mathfrak{g} is a multiple of κ , if G simple $\neq \mathbb{R}$

let $\text{aut}(\mathfrak{g})$ be the lie algebra of $\text{Aut}(\mathfrak{g})$, the group of Automorphisms of the lie algebra.

Proposition: Assume \mathfrak{g} is semi-simple.

the map $u \mapsto \text{ad}(u)$ is an isomorphism of \mathfrak{g} with $\text{aut}(\mathfrak{g})$

(Humphreys)

Proposition: $K \subset G$, and $\kappa|_K < 0$; then K is compact

Theorem (Nomizu)

the isometry group of a symmetric space is semi-simple $\times \mathbb{R}^m$

A **Cartan involution** is a Lie algebra homomorphism ϕ such that

- ϕ is an involution
- $\text{Kill}(X, \phi(X)) < 0$

Example: $\phi(A) = -tA$ for $\mathfrak{sl}_n(\mathbb{R})$

Proposition (non trivial)

(i) Cartan involutions exist!

see below

(ii) All Cartan involutions are conjugated.

} think of $\mathfrak{sl}_n(\mathbb{R})$

↳ prove next time

(easy version of (ii), each connected component is a G -orbit of (**))

$$\phi \longrightarrow \mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p} \text{ with } \phi|_{\mathfrak{k}} = 1, \phi|_{\mathfrak{p}} = -1$$

Proposition: ϕ Cartan involution $\Rightarrow [\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}, [\mathfrak{p}, \mathfrak{p}] \subset \mathfrak{p}, [\mathfrak{k}, \mathfrak{p}] \subset \mathfrak{p}$
and $\text{Kill}|_{\mathfrak{k}} < 0, \text{Kill}|_{\mathfrak{p}} > 0$

(the converse is true, given $\mathfrak{k}, \mathfrak{p}$ as above and ϕ defined by $\phi|_{\mathfrak{k}} = 1, \phi|_{\mathfrak{p}} = -1$
then ϕ is a Cartan involution)

Exercise: \mathfrak{k} Lie algebra of a compact group

III: Construction and properties of symmetric spaces. Let \mathfrak{g} be a semi-simple Lie algebra

$$\text{Sym}(\mathfrak{g}) := \{\text{Cartan involutions}\} \overset{\phi}{\subset} \underset{\text{submanifold}}{\text{Aut}(\mathfrak{g})}$$

\approx Maximal compacts of G
(we shall prove that later)

Exercise: show that $\text{Sym}(\mathfrak{g})$ is a manifold (Hint: use the constant rank theorem).

Our goal is

- (i) to show that $\text{Sym}(\mathfrak{g})$ is a symmetric space whose isometry group is (up to connected component g), and show that it has non-positive curvature
- (ii) to provide a gauge theoretic description of $\text{sym}(\mathfrak{g}) = S(G)$
- (iii) explain NAH for adjoint groups.

Let us make the following definition (just for this lecture)

A **Metric flat bundle** over a manifold M is a quadruple (\mathcal{G}, D, ρ) so that

- (i) \mathcal{G} is a \mathfrak{g} -bundle
- (ii) D is a flat connection
- (iii) ρ section of $\text{Aut}(\mathcal{G})$ by Cartan involutions

Proposition given D, ρ , let $\omega = \rho D \rho \in H^1(M, \mathfrak{g})$ then

- $D\rho = \frac{1}{2}[\rho, \text{ad}(\omega)]$
- $d^D\omega + \frac{1}{2}[\omega \wedge \omega] = 0$
- $\rho\omega = -\omega$

ω will be called the **Maurer-Cartan form**.

Not fearing redundancies we write the data (\mathcal{G}, D, ρ) as $(\mathcal{G}, D, \rho, \omega)$

■ Construction of the Maurer-Cartan form and (a)

For any (linear) group H $T_{\mathbb{R}}H = \mathbb{R} \cdot \frac{d}{dt}$

Thus if $\dot{\nu} \in T_{\nu} S(G) \subset T_{\nu} \text{Aut}(\mathfrak{g})$

$$\dot{\nu} \in \nu \cdot \text{aut}(\mathfrak{g}) = \nu \cdot \text{ad}(\mathfrak{g})$$

thus we have ω so that $\dot{\nu} = \nu \cdot \omega(\dot{\nu})$

since $\nu^2 = 1$; $\nu \dot{\nu} + \dot{\nu} \nu = 0$.

ω_0 is with values in $\mathcal{P} := \{u \in \mathfrak{g} ; \rho(u) = -u\}$

It follows that $\rho \cdot \text{ad}(\omega) + \text{ad}(\omega) \cdot \rho = 0$.

this also means $\rho[\omega(u), v] = -[\omega(u), \rho v]$

since ρ is an automorphism of \mathfrak{g} ; $\rho[\omega(u), v] = [\rho \omega(u), \rho(v)]$

thus $\rho(\omega(u)) = -\omega(u)$.

It follows that ω is with values in \mathcal{P}

(b) The Maurer-Cartan equation

$$\phi: \text{Sym}(\mathfrak{G}) \rightarrow \text{End}(\mathfrak{G}) \quad dO(u) = \phi \cdot \text{ad}(\omega(u))$$

$$\text{thus } 0 = d^2\phi = \phi \text{ad}(d\omega) + d\phi \wedge \text{ad}(\omega)$$

$$0 = \phi \cdot \text{ad}(d\omega) + \phi \cdot (\text{ad}(\omega) \wedge \text{ad}(\omega)) = \phi \left(\text{ad}(d\omega) + \frac{1}{2} [\text{ad}(\omega) \wedge \text{ad}(\omega)] \right)$$

$$\text{thus } 0 = \text{ad}(d\omega + \omega \wedge \omega) \quad \blacksquare \blacktriangleright$$

Proposition: $\text{Sym}(\mathfrak{g})$ carries a canonical (G, D_0, ρ, ω_0) for which ω is injective.

- ◀ D_0 is the trivial connection on $S(G) \times \mathfrak{g}$. The section ρ_0 is the tautological one which associates to a point of $S(G)$, itself seen as an element of $\text{Aut}(\mathfrak{g})$. ▶

III another point of view: the unitary connection.

let (g, D, ρ, ω) be a metric data on M

$$\text{let } \nabla = \mathcal{D} + \frac{1}{2} \text{ad}(\omega); \quad \nabla_X \xi = \mathcal{D}_X \xi + \frac{1}{2} [\omega(X), \xi]$$

Proposition (i) $\nabla \text{kill} = 0$

(ii) $\nabla \rho_0 = 0$, and thus ∇ is unitary

(iii) $d^\nabla \omega_0 = 0$, and $\rho_0 \omega_0 = -\omega_0$

(iv) $R^\nabla = \frac{1}{2} \text{ad}[\omega \wedge \omega]$

◀ (i) $\nabla \text{kill} = 0$, because $\text{ad}(\omega)$ is antisymmetric for Killing

$$\begin{aligned} \text{(ii)} \quad [\nabla_u \rho_0](v) &= \nabla_u [\rho_0(v)] - \rho_0[\nabla_u v] \\ &= [\mathcal{D}_u \rho_0](v) + \frac{1}{2} [\text{ad}(\omega(u), \rho)] v \end{aligned}$$

$$\text{But } \mathcal{D}_u \rho_0 = \frac{1}{2} [\rho, \text{ad}(\omega)] = -\frac{1}{2} [\rho, \text{ad}(\omega)]$$

$$\begin{aligned} \text{(iii)} \quad d^\nabla \omega_0(u, v) &= \nabla_u (\omega_0(v)) - \nabla_v (\omega_0(u)) - \omega_0[u, v] \\ &= \mathcal{D}_u \omega_0(v) - \mathcal{D}_v \omega_0(u) - \omega_0[u, v] \\ &\quad + \frac{1}{2} [\omega_0(u), \omega(v)] - \frac{1}{2} [\omega_0(v), \omega(u)] \\ &= d^\mathcal{D} \omega_0 + \frac{1}{2} [\omega_0 \wedge \omega_0] = 0 \end{aligned}$$

$$\begin{aligned} \text{(iv)} \quad \text{Finally, } R^\nabla &= R^\mathcal{D} + \frac{1}{2} \text{ad}(d^\mathcal{D} \omega) + \text{ad}[\omega \wedge \omega] \\ &= \frac{1}{2} \text{ad}[\omega \wedge \omega] \quad \blacktriangleright \end{aligned}$$

Dictionary

unitary $\nabla \longleftrightarrow \mathcal{D}$ flat

$$\nabla - \mathcal{D} = \frac{1}{2} \text{ad}(\omega_0), \quad \mathcal{D} \rho_0 = \frac{1}{2} [\rho_0, \text{ad}(\omega_0)]$$

$$\left. \begin{aligned} d^\nabla \omega_0 &= 0 \\ \nabla \rho_0 &= 0 \\ R^\nabla &= \frac{1}{2} \text{ad}(\omega_0 \wedge \omega_0) \end{aligned} \right\} \longleftrightarrow \left\{ \begin{aligned} d^\mathcal{D} \omega_0 + \frac{1}{2} [\omega_0 \wedge \omega_0] & \text{ (Maurer-Cartan equations)} \\ \mathcal{D} \rho_0 &= \frac{1}{2} [\rho_0, \text{ad}(\omega_0)] \\ R^\mathcal{D} &= 0 \end{aligned} \right.$$

Exercise: for $G = \text{SL}_2(\mathbb{R})$, recognize the Minkowski model.

IV. Application 1 : maps into symmetric spaces/ NAH for general adjoint

let $f : M \rightarrow \text{Sym}(\mathfrak{g})$, then we obtain by pull back from the canonical data $(g_0, D_0, \rho_0, \omega_0)$ a metric data $(f^*g_0, f^*D_0, f^*\rho_0, f^*\omega_0)$ on M

Remark 1. We also have g, ∇, ρ, ω where $\nabla \rho = 0; \nabla \omega = 0, R^\nabla = \frac{1}{2} \text{ad}[\omega, \omega]$

Conversely :

Proposition let (g, D, ρ, ω) be a flat metric bundle on M , $\pi_1(M) = 0$

Then there exists a map $f : M \rightarrow \text{Sym}(\mathfrak{g})$ unique up to the G action, so that $(f^*g_0, f^*D_0, f^*\rho_0, f^*\omega_0) = (g, D, \rho, \omega)$

◀ let $D = \nabla - \frac{1}{2} \text{ad}(\omega)$, then

(i) : then D is flat, thus $g = g \times M$

(ii) ρ becomes : $M \rightarrow \text{Sym}(\mathfrak{g})$

(iii) and we have $D\rho = \frac{1}{2} [\rho, \text{ad}(\omega)]$ ($\nabla \rho = 0$)

$\Leftrightarrow D\rho = \rho \cdot \omega$ ($Dg = g Dg^\#$) ▶

NAH for a general adjoint (complex) group.

A harmonic mapping on a surface X

is given by

a G -Higgs bundle

(G, ϕ)

$(G, \nabla, \rho, \omega)$

(i) $R^\nabla + \frac{1}{2} \text{ad}[\omega, \omega] = 0$ look for ρ

(ii) $\rho \omega = -\omega$

(iii) $d^\nabla \omega = 0$

(iv) $\nabla \rho = 0$

(v) $\omega^{1,0}$ is holomorphic

(Hitchin)



(i) $G, \phi, \bar{\partial}$

$[\bar{\partial} = \bar{\partial}^\circ]$

$\phi = \omega^{1,0}$

look for ρ
then $\omega = \rho D\rho$



$\mathcal{D} = \nabla - \frac{1}{2} \text{ad}(\omega)$

flat connection

V. Application 2: $\text{Sym}(G)$ as a symmetric space

the metric on $\text{Sym}(G)$ is defined as $\langle x|y \rangle = \text{kill}(\omega(x), \omega(y))$

the connection $\nabla^{\text{lc}} = \omega^* \nabla^\circ$ is metric ($\nabla_{\rho_0}^\circ = 0$) and torsion free ($d^\nabla \omega_0 = 0$)

Thus the curvature of the metric is given by

$$R^\circ(x, y)z = [[\omega(x), \omega(y)], \omega(z)]$$

$$\langle R^\circ(x, y)z | w \rangle = - \langle [\omega(x), \omega(z)] | [\omega(y), \omega(w)] \rangle + \langle [\omega(x), \omega(w)] | [\omega(y), \omega(z)] \rangle$$

In particular, using Jacobi identity.

$$\langle R^p(x, y)Y|X \rangle = - \|[w(x), w(y)]\|^2 \leq 0$$

Exercise :

1) $\text{Sym}(G)$ is a manifold

2) each connected component is a G -orbit.

We will now interpret

$\mathfrak{g} \subset$ Lie algebra of vector fields on $M := \text{Sym}(G)$

proposition

(i) $\mathfrak{k}_x = \{u \in \mathfrak{g}, u(x) = 0\}$

(ii) let K be the connected Lie group whose Lie algebra is \mathfrak{k}
 If K fixes x , then $\mathfrak{k} \subset \mathfrak{k}_x$

◀ (i) Follows from the fact

$\mathfrak{g} \rightarrow \mathcal{X}(M)$ is given by

$g(x) = \pi_P(g)$ where π_P is the \perp projection on \mathcal{P}

(ii) is a consequence of (i) : If K fixes x , then $\forall u$ in \mathfrak{k} $u(x) = 0$. ▶

Proposition. let x be a point on $\text{Sym}(G)$, let i_x be the conjugation by x $i_x: \sigma \mapsto x\sigma x^{-1}$,

(i) then i_x acts by isometries on $\text{Sym}(G)$

(ii) x is the unique fixed point of i_x on $\text{Sym}(G)$

(iii) $T_x i_x = -1$

Hint for (ii) $i_x(y) = y \iff \rho_x$ and ρ_y commutes

\Rightarrow then K_x is stable by ρ_y : $K_x + K_y$ stable by ρ
 but $\text{Kill}(K_x + K_y) < 0 \Rightarrow$ contradiction

Consequence: $\text{Sym}(\mathfrak{g})$ is simply connected and connected.

let M_0 be a connected component of $\text{Sym}(\mathfrak{g})$

(i) M_0 does not contain a closed geodesic γ

 indeed (avoiding covering of your loop)

one can find $x \neq y$ in γ so that the length of two arcs are the same (otherwise γ is a double cover)

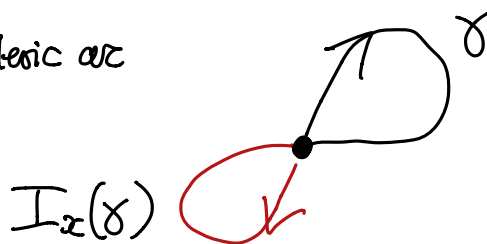
then I_x fixes y as well



thus $x = y$ contradiction

(ii) Assume M is not simply connected then we get

a geodesic arc



then $\gamma \cup I_x(\gamma)$ is a closed geodesic

Thus M_0 is simply connected

let K_y associated to y and C a compact orbit of K_y , in M_0

then the center construction, produces m in K_y fixed by m

thus $m = y$ in M_0 \blacktriangleright

Center construction in $K \leq O$: Given a compact C in a connected simply connected M with $K \leq O$; there exists x, R unique so that (i) $C \subset B(x, R)$; $R = \inf\{r \mid \exists y \ B(y, r) \supset C\}$

Corollary : all maximal compact subgroups are conjugated.
(every compact subgroup is contained in the stabilizer of a Cartan involution)

VI Reductive subgroup of G . A reductive algebra of \mathfrak{g} is a subalgebra \mathfrak{h} so that $\text{kill}|_{\mathfrak{h}}$ is non degenerate.

Proposition

(i) If $\mathfrak{h} \subset \mathfrak{g}$ is reductive, then $\mathfrak{h} = \mathbb{Z}(\mathfrak{h}) \times \mathfrak{l}$, where \mathfrak{l} is semi-simple and $\mathbb{Z}(\mathfrak{h})$ is the center of \mathfrak{h}

(ii) \mathfrak{h} is reductive if and only if there is an involution $i_{\mathfrak{h}}$ of \mathfrak{h} so that $\mathfrak{h} = \{u \mid i(u) = u\}$

(iii) let $i_{\mathfrak{h}}$ be an involution of \mathfrak{g} , then

$W = \{ \text{Cartan involution } i, \text{ so that } i_{\mathfrak{h}} \cdot i = i \cdot i_{\mathfrak{h}} \}$

is a non empty, totally geodesic subspace of $\text{Sym}(\mathfrak{g})$

(iv) If $\mathfrak{h} = \mathbb{Z}(\mathfrak{h}) \times \mathfrak{l}$, then $W_{\mathfrak{h}} = \mathbb{Z}(\mathfrak{h}) / \mathbb{Z}_{\mathfrak{h}}(\mathfrak{h}) \times \text{Sym}(\mathfrak{l})$

reductive subalgebra \iff involutions \iff totally geodesic subspace

Another characterisation of $W = \{ z \mid i_{\mathfrak{h}}(z) = z \}$

non empty because $z \bullet \overset{+}{\underset{m}{\circ}} \bullet i_{\mathfrak{h}}(z)$ m is fixed by $i_{\mathfrak{h}}$