

# I Non positively curved manifolds

Proposition: Assume  $M$  is complete with  $K \leq 0$ , then  $\exp: T_m M \rightarrow M$  is a local diffeomorphism.

A **Hadamard manifold** is a complete Riemannian manifold, simply connected, with  $K \leq 0$ . Then  $\exp_m: T_m M \rightarrow M$  is a diffeomorphism.

In particular, given  $x$  and  $y$  there exists a unique geodesic between  $x$  and

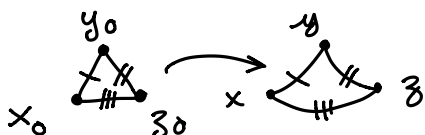
let  $M$  be a metric space and  $x, y, z \in M$ , the comparison triangle is the triangle  $V_0 = (x_0, y_0, z_0)$  in  $\mathbb{R}^2$  so that

$$d(x, y) = \|x_0 - y_0\|, \quad d(y, z) = \|y_0 - z_0\|, \quad d(x, z) = \|x_0 - z_0\|$$

The comparison map is

$$\partial T_0 = [x_0, y_0] \cup [z_0, x_0] \cup [y_0, z_0] \longrightarrow [x, y] \cup [z, x] \cup [y, z]$$

$\uparrow$  geodesic segments



Proposition [CAT(0)]

For any  $(x, y, z)$  in  $M$ , the comparison map is contracting.

Moreover, if the comparison map preserves the metric.

The comparison map extends to a totally geodesic isometric embedding from  $T_0$  to  $M$ .

Corollary [flat strip]: If  $\gamma_1$  and  $\gamma_2$  are two geodesics within

Bounded distance:  $\exists A; d(\gamma_1(t), \gamma_2(t)) < A$ . then

There exists a totally geodesic isometric embedding

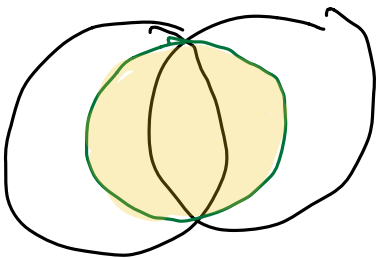
$$\gamma: [0, b] \times \mathbb{R} \longrightarrow M \text{ so that}$$

$$\gamma|_{\{0\} \times \mathbb{R}} = \gamma_1; \quad \gamma|_{\{b\} \times \mathbb{R}} = \gamma_2$$

proposition [Convexity of the metric]

let  $\gamma_1$  and  $\gamma_2: \mathbb{R} \rightarrow M$  be two geodesics in some Hadamard manifold; then

$t \mapsto d(\gamma_1(t), \gamma_2(t))$  is a convex function



Corollary let  $m$  be the middle of  $x \neq y$   
then  $\forall R, \exists r < R \quad B(m, r) \supset B(x, R) \cap B(y, R)$

Corollary: if  $C$  is a compact set; then exists a unique  $x, R$  so that  $C \subset B(x, R)$ ; and if  $C \subset B(y, R')$  then  $R' > R$   
 $x$  is the center of  $C$ .

[Infinitesimal version of the convexity property]

let  $\gamma$  be a geodesic, if  $\gamma_t$  is a family of geodesics then



$J = \frac{\partial}{\partial t} \gamma_t$ , vector field along  $\gamma$  is a

Jacobi field; it satisfies  $\nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} J = R(\dot{\gamma}, J)\dot{\gamma}$  (with a sign)

Proposition

If  $J$  is a Jacobi field  $\|J_{\gamma(t)}\|^2$  is a convex function of  $t$

Moreover if  $\|J_{\gamma(t)}\|$  is constant then  $R(\dot{\gamma}, J)\dot{\gamma} = 0$  and  $J$  is //

Consequence

Proposition . The energy is a convex function of the set of mappings  $M \rightarrow N$  (if  $N \leq 0$ ):

If  $f_t$  is a family of maps so that  $\forall x \quad f_t(x)$  is a geodesic then

(i)  $t \rightarrow \left\| \frac{\partial f_t}{\partial t} \right\|^2$  is convex

(ii)  $E(f_t)$  is convex.

◀ Indeed  $\forall u; \mathbb{T}_x \mathbb{F}_t(u)$  is a Jacobi field by definition ▶

## II Buseman / horofunction compactification

let  $M$  be a metric space. The **Busemann embedding** The map  
 $M \rightarrow C^\infty(M) / C^{\text{st}} \text{ function}, x \mapsto d_x : (y \mapsto d(x, y))$

lemma let  $M$  be metric so that balls are compact  
then the image of  $M$  by  $i$  is relatively compact.

Def: The **Busemann compactification** is  $\overline{i(M)}$ ;

A **Busemann function (or horofunction)** is an element of  $\overline{i(M)} \setminus i(M)$   
by a slight abuse of language a representative of  $h$  in  $C^*(M)$  will also be called a Busemann function.

Fixing a point  $m_0$  in  $M$ , one can identify  $C^\circ(M) / \text{const}$  with  
 $\{f \in C^\circ(M) / f(m_0) = 0\}$

Then  $h$  is an horofunction if there exists a sequence  $x_i$  so that

$$h(m) = \lim_{x_i \rightarrow \infty} (d(x_i, m) - d(x_i, m_0))$$

Proposition if  $x_i \in M \rightarrow$  Busemann function  $h$ ,  
then if  $d(y_i, x_i) \leq K$ ; then  $y_i \rightarrow h$

Assume  $K(M) \leq 0$ ; let  $\mathcal{H}_\infty M = \{ \text{space of horofunctions} \}$

Proposition given any  $x \in M$ ; there exists a unique  
geodesic  $\gamma$  so that  $h(\gamma(t)) = t + c$

[gradient line of  $h$ ]

Moreover  $\lim_{t \rightarrow \infty} \gamma(t) = [h]$

◀ Exercise on the triangular inequality ▶

## Corollary

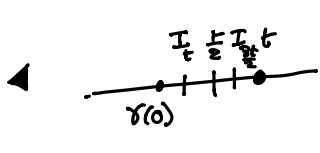
Assume that  $g \in \text{Isom}(M)$  satisfies

$g(\gamma(t)) = \gamma(t+b)$  where  $\gamma$  is a gradient line of  $h$ ;

Then  $g[h] = h$

Corollary: Assume  $M$  is a symmetric space; let  $h$  be a Busemann function

Then  $\text{Stab}_G[h]$  is a non trivial sub algebra of  $G$ .



$$I_{\frac{3t}{2}} \cdot I_{\frac{t}{2}} \rightarrow \text{Id.}$$

$$g(t); g_t(\gamma(0)) = \gamma(t), g_t \text{ preserves } \gamma \text{ globally}$$

$$\text{thus } g_t(\gamma(s)) = \gamma(s+t)$$

let  $H = \text{Stab}[h]$ ; this is a closed subgroup of  $G$ , hence a lie subgroup, and since it contains element arbitrarily close to

the identity it follows that  $\mathfrak{h} \neq \{0\}$

• Exercise (if  $M$  has no euclidian factor)  $\mathfrak{h} \neq \mathfrak{g}$

Theorem let  $\Gamma$  be a subgroup of  $G = \text{Isom}(\text{Sym}(\mathfrak{g}))$ , if  $\mathfrak{g}$  is simple.  $\Gamma$  preserves a Busemann function, then  $\Gamma$  is not Zariski dense

◀ If  $\Gamma$  preserves  $[h]$ , then  $\Gamma \subset \text{Stab}[h]$ ; and in

particular  $\Gamma \subset \text{Normalizer}(\mathfrak{h}) =$  algebraic subgroup

of  $\text{Ad}(\mathfrak{g})$ ; non trivial if  $\mathfrak{g}$  is semi simple (otherwise  $\mathfrak{h}$  is an ideal)

## III Harmonic mappings.

### 1. Some general properties

Proposition 2: let  $f: M \rightarrow N$  be a harmonic mapping and  $g$  be a convex function on  $N$ ; then

$$\Delta f \circ g \geq 0$$

### Proposition [Maximum principle]

Let  $f: N \rightarrow \mathbb{R}$ ;  $N$  Riemannian, let  $f$  be a function so that  $\Delta f \geq 0$ ; assume that  $f$  has a maximum at  $m_0$ , then  $f$  is constant.

### 3. Uniqueness of harmonic mappings

Given  $f, g: M \rightarrow N$  which are  $\rho$ -equivariant

$\Rightarrow F: [0, 1] \times M \rightarrow N$ ,  $F(0, x) = f(x)$ ;  $F(1, x) = g(x)$ ,  $t \mapsto F(t, x)$  is a constant speed geodesic.

$$\Rightarrow u(x) = TF\left(\frac{\partial}{\partial t}\right)$$

Def:  $f$  and  $g$  are **parallel**, if  $u$  is parallel along  $F: \nabla_X u = 0$  and  $\forall v \in TM$ ,  $\langle R(TF(\sigma), u)TF(\sigma)(u) \rangle = 0$

Theorem if  $f$  and  $g$  harmonic mappings:  $M \rightarrow N$  then  $f$  and  $g$  are parallel.

Let  $f_t$  as before, then  $E(f_t)$  is convex, since it is critical at  $t=0$  and  $t=1$ , it is constant on  $[0, 1] \Rightarrow E(f_t)$  is also constant  $\Rightarrow \forall u; \|TF_t(u)\| = \text{const}$ .

Trick If  $g_1 + g_2 = \text{const}$ ,  $g_1$  and  $g_2$  convex, then  $g_1, g_2$  are const.

Since  $TF_t(w)$  is a jacobian field along  $f_t(x)$   $\begin{matrix} f_t(x) \\ w \\ f_t(x) \end{matrix}$

$\Rightarrow \nabla_u w = 0 \Rightarrow \nabla_w u = 0$ , parallel  $\blacktriangleright$

Corollary: If  $\phi: T^n \rightarrow N$  harmonic map then  $\phi$  is totally geodesic;

$\blacktriangleleft$  Compare  $\phi$  and  $\phi \circ T_g = \text{translation}$   $\blacktriangleright$